

SKiiP 35NAB126V1



MiniSKiiP® 3

3-phase bridge rectifier +
brake chopper + 3-phase
bridge inverter
SKiiP 35NAB126V1

Features

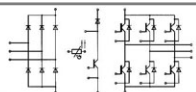
- Fast Trench IGBTs
- Robust and soft freewheeling diodes in C&AL technology
- Highly reliable spring contacts for electrical connections
- UL recognised file no. E63532

Typical Applications*

- Inverter up to 28 kVA
- Typical motor power 15 kW

Remarks

- V_{CEsat} , V_F = chip level value



NAB

Absolute Maximum Ratings		$T_B = 25^\circ\text{C}$, unless otherwise specified	
Symbol	Conditions	Values	Units
IGBT - Inverter, Chopper			
V_{CES}		1200	V
I_C	$T_B = 25 (70)^\circ\text{C}$	73 (55)	A
I_{CRM}		100	A
V_{GES}		± 20	V
T_J		-40 ... +150	$^\circ\text{C}$
Diode - Inverter, Chopper			
I_F	$T_B = 25 (70)^\circ\text{C}$	62 (46)	A
I_{FRM}		100	A
T_J		-40 ... +150	$^\circ\text{C}$
Diode - Rectifier			
V_{RRM}		1600	V
I_F	$T_B = 70^\circ\text{C}$	61	A
I_{FSM}	$t_p = 10 \text{ ms, sin } 180^\circ, T_J = 25^\circ\text{C}$	700	A
i^2t	$t_p = 10 \text{ ms, sin } 180^\circ, T_J = 25^\circ\text{C}$	2400	A^2s
T_J		-40 ... +150	$^\circ\text{C}$
Module			
I_{RMS}	per power terminal (20 A / spring)	80	A
T_{stg}		-40 ... +125	$^\circ\text{C}$
V_{Isol}	AC, 1 min.	2500	V

Characteristics		$T_B = 25^\circ\text{C}$, unless otherwise specified			
Symbol	Conditions	min.	typ.	max.	Units
IGBT - Inverter, Chopper					
V_{CEsat}	$I_{Cnom} = 50 \text{ A}, T_J = 25 (125)^\circ\text{C}$		1,7 (2)	2,1 (2,4)	V
$V_{CE(TH)}$	$V_{GE} = V_{CE}, I_C = 2 \text{ mA}$	5	5,8	6,5	V
$V_{CE(TO)}$	$T_J = 25 (125)^\circ\text{C}$		1 (0,9)	1,2 (1,1)	V
r_T	$T_J = 25 (125)^\circ\text{C}$		14 (22)	18 (26)	m Ω
C_{iss}	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$		3,7		nF
C_{oss}	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$		0,8		nF
C_{res}	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$		0,7		nF
$R_{\theta(j-s)}$	per IGBT		0,55		K/W
$t_{i(on)}$	under following conditions		85		ns
t_r	$V_{CC} = 600 \text{ V}, V_{GE} = \pm 15 \text{ V}$		30		ns
$t_{i(off)}$	$I_{Cnom} = 50 \text{ A}, T_J = 125^\circ\text{C}$		430		ns
t_f	$R_{con} = R_{Coff} = 12 \Omega$		90		ns
E_{on}	inductive load		6,5		mJ
E_{off}			6,1		mJ
Diode - Inverter, Chopper					
$V_F = V_{EC}$	$I_{Fnom} = 50 \text{ A}, T_J = 25 (125)^\circ\text{C}$		1,6 (1,6)	1,8 (1,8)	V
$V_{(TO)}$	$T_J = 25 (125)^\circ\text{C}$		1 (0,8)	1,1 (0,9)	V
r_T	$T_J = 25 (125)^\circ\text{C}$		12 (16)	14 (18)	m Ω
$R_{\theta(j-s)}$	per diode		1		K/W
I_{FRM}	under following conditions		71		A
C_{rr}	$I_{Fnom} = 50 \text{ A}, V_{RR} = 600 \text{ V}$		11,5		μC
E_{rr}	$V_{GE} = 0 \text{ V}, T_J = 125^\circ\text{C}$		4,7		mJ
	$di_F/dt = 1900 \text{ A}/\mu\text{s}$				
Diode - Rectifier					
V_F	$I_{Fnom} = 35 \text{ A}, T_J = 25^\circ\text{C}$		1,1		V
$V_{(TO)}$	$T_J = 150^\circ\text{C}$		0,8		V
r_T	$T_J = 150^\circ\text{C}$		11		m Ω
$R_{\theta(j-s)}$	per diode		0,9		K/W
Temperature Sensor					
R_{ts}	$\pm 3\%, T_r = 25 (100)^\circ\text{C}$		1000(1670)		Ω
Mechanical Data					
w			95		g
M_b	Mounting torque		2	2,5	Nm

